LIDAR



VERMONT SOCIETY of **LAND SURVEYORS**

J. Thaddeus "Thadd" Eldredge *ELDREDGE SURVEYING & ENGINEERING, LLC* 1038 Main Street, Chatham, MA 02633 www.ese-llc.com

J. THADDEUS "THADD" ELDREDGE

- BA in Theoretical Mathematics, Colby College
- PLS Certificate from Wentworth Institute of Technology
- PLS 46471, MA
- Soil Evaluator, MA
- Certified Floodplain Manager, USA
- Has a fancy pants name; goes by Thadd.
- I will try to not put you to sleep.

WHAT IS LIDAR?

- Laser Radar
- Light Detection and Ranging
 - Scanning



Lidar (also written LIDAR, LiDAR or LADAR) is a remote sensing technology that measures distance by **illuminating a target with a laser and analyzing the reflected light.** Although thought by some to be an acronym of Light Detection And Ranging,[1] the term lidar was actually created as a portmanteau of "light" and "radar".

[2][3] Lidar is popularly used as a technology to make high-resolution maps, with applications in geomatics, archaeology, geography, geology, geomorphology, seismology, forestry, remote sensing, atmospheric physics, airborne laser swath mapping (ALSM), laser altimetry, and contour mapping. (wikipedia) SURVEYING!!!

WHO IS USING LIDAR?

• Aerial



Oyster Bay Lane

Sullivan

Stream Analysis

Video Sources:

2014 NOAA Aerial LiDAR "Post-Sandy"

ELDREDGE SURVEYING & ENGINEERING, LLC

1038 Main Street, Chatham, MA 02633

www.ese-llc.com

POINT CLOUD FORMATS

Rapidlasso - *.las and *.laz ASTM – *.e57 Text - *.xyz and *.pts

There are more.

Text formats are valid and you can make your own point clouds! X,Y,Z X,Y,Z X,Y,Z

E57 is being developed by a committee within the American Society for Testing and Materials. It may one day be the universal standard for imagery and scan data.



rapid<mark>las</mark>so

I like the LAS and LAZ formats the best. LAZ is the most compact format. The Vermont LiDAR all seems to be in LAS format. https://rapidlasso.com/

- Downloadable tools with a rough GUI. Some are open license and others require licensing.
- Downloadable toolboxes for:
 - ARC
 - QGIS

SURVEY POINTS V. POINT CLOUD

- Surveyed Points (smart)
- Few
- Specific targets That point is along that edge of pavement and that one is at the building corner.
- Described Even when the descriptor is cryptic, there is still something there.

- Scanned Points (dumb)
- Many
- Unspecific targets That point is on an object and I don't know if it is at the edge of the pavement or right at the building corner.
- Undescribed That point is on an object and when I look at the 2000 points around it plus the imagery, I see a bush.

ATTRIBUTES

THESE ARE MORE THAN JUST POINTS

Point Query		×	Code	Description	
Point Query		~	0 []	Created, never classified	
odel: Job313664_2013_2014_	_usgs_post_sandy_ma_nh_ri			Unclassified	
			2	Ground	
Model Info	Source File Info			Low Vegetation Medium Vegetation	
1 066 735 22 ft	File	Job313664 2013 2014 usos post sandy ma nh rilas		High Vegetation	
• 2 720 602 22 ft	Folder	C\\Llsers\\Thadd\\AnnData\\Loca\\Temp\\OTTempEilesEolder\\TMP65B0 tmp\\	□6	Building	
. 2,720,092,32 ft	v.	1.056 735 000 H	07	Low Point (Noise)	
. 70.37 ft	A. V.	1,000,755,220 ft		Model Key-point (mass point)	
itensity: 248	7.	2,720,092.320 II		Water	
		76.575 TOOL		Rairoad	
	Intensity:	24/		Overlan	
	Return Number:	1		Wire - Guard (Shield)	
	Number Returns:	1	14	Wire - Conductor (Phase)	
	Scan Direction:	1	15	Transmission Tower	
	Line Edge:	0	16	Wire-structure Connector	
	Classification:	18	17	Bridge	
	Classification (8-Bit):	18		High Point (Noise)	
	Scan Angle:	12.7559 deg		Reserved for ASPRS Definition	
	User Data:	0		Enable All Disable All	
	Point Source ID:	1,251	- Return 1	vpes to Display	
	Withheld:	0	Return	Туре	
	Synthetic:	0	🗹 Unk	nown	
	Keypoint:	0	First		
	Time:	80.836.473.4150913 sec (RAW)	Sec.	ond	
			✓ Las		
			I Sing	le	
eate Marker Here	V Dolt	Copy to Clipboard Help Close	First	-ot-Many	

SOFTWARE

http://www.ese-llc.com/lidar - This is a dumping ground webpage for links to LiDAR software.

Software you may have:	<u>Free Software:</u>				
ESRI ARC 10.1 or greater	Fugro Viewer – Great for surface vis	ualization. Will export points and lines to SHP files.			
AutoDesk Civil3d	Quick Terrain Viewer – Great for viewing. Measurement and listing of points available.				
AutoDesk ReCap	LasTools – A tool for manipulating, converting or otherwise using clouds.				
QGIS	Fusion – US Forest Service tool for Trees				
	MeshLab – Will create 3d models from clouds				
	Cloud Compare – It will compare two	o clouds and more.			
	PointCloudViz – Viewer				
	SceneLT – View clouds				

Marketed Software:

Global Mapper – Great for all LiDAR types, best value
Carlson Point Cloud – Great for a surveyor using Carlson to get into clouds
TopoDOT – If you have MicroStation, it is an excellent product
Quick Terrain Modeler – Excellent tools for the toolbox.
Faro Scene – Stitches scans and extracts some data.
And More... (These are the ones that we have in the office)



Tilipi Run

Guillard

Coastal Bank

Video Sources:

2014 NOAA Aerial LiDAR "Post-Sandy"

ELDREDGE SURVEYING & ENGINEERING, LLC

1038 Main Street, Chatham, MA 02633

www.ese-llc.com

FUGRO VIEWER





Just an example from Pittsfield, VT. Heights are visualized by color.





Colored by Classification

Colored by Intensity





Colored by Source ID (Flightline)



Colored by Imagery

Colored by File (You need 2 files to see it.)



Colored by Return





With a few clicks, you can create a solid surface model from the previously classified ground points. Take a moment and pick out some features: River & Escarped Embankment

Roads & Driveways Trails & Paths Potential Stone Walls



The two potential walls adjacent to the field could very well be there. These could be picked out from aerial photography. If the one to the north is a stone wall, one would be hard pressed to find it in the aerials.

We have recovered dozens of ancient boundaries with the aerial lidar surface models. We have used these models to rough in deeds and prepare for the ground surveys to locate features on the ground.





Fugro allows you to create POI and AOI: Points of Interest and Areas of Interest. These can be exported to Shape Files, then used accordingly.

Please note that there are other items in the surface that can look like walls, paths, streams and other features. This can be a great starting point. It can help point those boots on the ground but cannot replace them.





Fugro will allow you to show the contours from the surface, but you cannot export them. There are image overlay options as well, go have some fun.





APPLIED IMAGERY

THE READER HAS SOME GREAT QUALITIES, BUT THE MODELER HAS SO MANY MORE.



Create Folder Index			-	
	×	Select File Type(s) to inc	ude: Select All	Clear All
Files Se	Searching Directory: Survey_Report earched: 6,447, Good Files: 305, Unregistered Files: 0 Bad Files: 0, Error Files: 0	LAS Point Files LAS Point Files LAS Point Files (NITF LAZ Point Files BPF Point Files CEOTTEE Files (DEM	Wrapped)	
Select Folder to Index	H:\LIDAR\0_7M\2014	Erdas Imagine Files (OT Modeler Model Fr	DEM & Imagery)	
Create KMZ Index File	C:\Users\Thadd\Desktop\0_7-2014.kmz	USGS DEM Files		
Create SHP Index File		Mr Sid Image Files		
Organize by Direct	ory Organize by File Type Recursive Subfolders	JP2K Image Files		
Generate Search C	ache?	Go	! Help	Close

×

EVT1993.las Open File: EVT1993.las File Size: 300,238 kb File Date: Fri Apr 24 14:00:41 2015 File Type: LAS File Signature: LASF File Source ID: 65,535 Adjusted GPS Time: 1 LAS Version: 12 System Identifier: Generating Software: TerraScan File Creation Date: April 23, 2015 Point Record Type: 1 Per-point Time: YES Per-point RGB: NO Total Points: 10,722,773 First Return: 8.253,471 Second Return: 1,769,002 Third Return: 577.287 Fourth Return: 111,667 Fifth Return: 10,830 Estimated GSD: 0.487 X File Precision: 0.010000 Y File Precision: 0.010000 Z File Precision: 0.010000 Georegistration Coordinate System: NAD_1983_2011_StatePlane_Vermont_FIPS_4400 Projection: Unknown Geographic CS: Unknown PCS Citation: NAD_1983_2011_StatePlane_Vermont_FIPS_4400|projection: Transverse Mercator Geographic Citation: GCS Name = GCS NAD 1983 2011[Datum = NAD 1983 2011|Ellipsoid = GRS 1980|Primem = Greenwich Vertical Citation: NAVD88 - Geoid12A (Meters) Horizontal Units: metre Vertical Units: metre Directions: To here - From here

Took a directory, made an index to KMZ. Found an interesting area in Google Earth. Listed the tiles and all kinds of information comes out.



☆ Tour Guide







An oblique view.



Created a surface with all the points.



USGS Earth Explorer (write that one down and google it or https://earthexplorer.usgs.gov)



Downloaded some 2013 High Resolution Orthoimagery.

	A
NOAA: Data Access View X	
← → C 🔒 https://coast.noaa.gov/dataviewer/#/ 🖈 🎇 :	
🗰 Apps ★ Bookmarks 📋 CAPE COD 📒 LiDAR 📒 COMPUTER 😒 NOAA: Data Access Vi 🚳 FEMA Flood Map Servi 🛛 👋 📋 Other bookmarks	
	VERMONT VERMONT
	Elevation
	(On some
	borders)
And Register Control of Control o	Imagery (A little)
DATA ACCESS VIEVVER	https://Coast.noaa.gov/dataviewer/#/
Discover, customize, and download authoritative data.	
Choose a Data Type to Explore	The USGS Earth Explorer delivers tiles on mostly in UTM Meters.
Imagery Land Cover Elevation	The NOAA viewer allows you to take
	random areas and converts them to any
	auctom vou'd like
	system you a like.



This makes for a great 3d visualization of the scene. Some spikes are from noise, others are along the power lines.



The points remain colorized.





CARLSON POINT CLOUD

Carlson PC is built on the Carlson methodology. It runs through CAD or IntelliCAD in its own window and menu.

I chose this program because of their excellent support for their other products. They have not failed that support with this module.





Beautiful Saquatucket Harbor, Harwichport, MA. There is noise from the water.

This was colorized from 2014 Aerial Imagery (3" pixel) and it was scanned (Mobile, FARO) in the early Fall, 2015. The outlying areas are based on 2014 Aerial LiDAR.

The point cloud module runs outside or alongside AutoCAD or IntelliCAD.

	ie 🍳 Camera 🥞	Action 🧿 Data	
election Set			
Add 🔘	Remove	Inside	Outside
Individual	Window	Perimeter	Polyline
All	None	Invert	Elevation
dit			
Information	Delete	Hide	Show All
Image	Smooth	Clean	
ransform			
Translate	Rotate	Scale	Sequence
xtract			
Breaklines	Contours	Profile	Sections
Bare Earth	Plane	Intersection	Polyline

Action

Selection – 8 tools to select point with 2 pairs of radios.

Edit – Hide, show, list and colorize the clouds. Smooth evens out meshes (think TINs) and Clean reduces points from a cloud (some get a little dense)

Transform – The transform functions will move the clouds.

Create -

Point – points with your F2F codes

Polylines – simple 3-d polylines

Cloud – Select an area and create a neww (smaller) cloud

Mesh – A surface

□Text – Text

 \Box Grid — Grid

Extract -

^DBreaklines – from a mesh

Dontours – from a mesh

Profile & Section – need a CL file in Carlson

Bare Earth – Creates a new cloud with the ground only

Plane – flat plane

Intersections – Intersects two planes

Polyline – Automatic extraction based on Intensity



A polyline was created along the centerline of the drive. At this vantage, it appears to be above and below the cloud.



The polyline can be quickly drawn into the open CAD session. The same goes for points and Field 2 Finish can be executed directly from the Point Cloud module.

The objects in a CAD drawing can be imported into the Point Cloud session.



The polyline can be used to show a slice of the cloud. The points shown here are along the flow line at the base of a Cape Cod Berm. The cloud has been vertically exaggerated by 3.

PointCloud Nov	6 2015 3DTK		X	😨 Scene less noise 01
Project 🐨 Sce	ene 🌯 Camera	Section O Data	a	File Edit Selection View Create Tools
Selection Set				[[] [] [] [] [] [] [] [] [] [] [] [] []
🖲 Add 🛛 🖲	Remove	Inside	Outside	
Individual	Window	Perimeter	Polyline	
All	None	Invert	Elevation	
Edit				
Information	Delete	Hide	Show All	
Image	Smooth	Clean]	
Transform				
Translate	Rotate	Scale	Sequence	Right-click to end perimeter
Create				
Point	Polyline	Cloud	Mesh	A CARACTER AND A CONTRACT OF A
Text	Grid			
Extract				
Breaklines	Contours	Profile	Sections	
Bare Earth	Plane	Intersection	Polyline	
Command Histor	ry -			
Creating and vie	wing Scene "Scene	ie less noise 01"		
Successfully add	ed Region 1 to le	ss noise		
			-	venus caggerour 10
				X: 1049/72.670 Y: 2707982.345 Z: 7.848

The cloud is being viewed by height. The red is a selection set to be isolated.



Some additional isolation and resetting the range for height coloration shows the trees.



The software has tree extraction functions that work best with isolated trees. It will provide a coded descriptor with caliper, height and spread.



Isolating another part of the cloud allows for the quick extraction of the utility poles. The lines show up and the height above a road can be determined.



If you can see this building, then good. The blue patches are planes extracted from visible sides. These can be intersected to form corners. The can also be imported into 3d CAD.



The other side of the building.



Global Mapper v16.1 (b041015) [64-bit] [+Lidar] - REGISTERED	— í	٥	>
File Edit View Tools Analysis Search GPS Help			
Image: Set up Favorites List. Im			
199990 Redello			





Colchester, VT



USGS Earth Explorer does have some high resolution orthoimagery.

The cloud is still there, it has been colorized based on the imagery.





This is just colorized cloud.



Just the ground points.

A surface model. This is very similar to the Fugro surface model.





It looks like some trails and some geology atop this rock.

Contours can be created and exported to CAD or SHP. Surface models can be exported.



Linework can be determined and extracted (Digitized)





Automatic Classification of Ground Points		×
Select Unclassified Point Cloud(s) to Find Likely G	Ground Points In	
EVT1488.las		
🔲 Only Classify Lidar Points Selected in Digitize	er Tool	
Base Bin Size to Check for Curvature Deviations:	2 Meters	-
Specify the minimum height above the local aver in order to be considered a non-ground point. Li- from local averages to make a point non-ground 0.3	age minimum elevation that a point has to arger values require greater vertical deviat 	be ion
Removal of Likely Non-Ground (i.e. Building/Vege	etation) Points	
The following parameters control the automatic points using a morphological filter. Use larger slo and/or large buildings (skyscrapers).	remove of likely non-ground (i.e. building) pe and height delta in areas with high relie	f
Maximum Height Delta: 100 meters	(use larger values for high relief/tall buildir	ngs)
Expected Terrain Slope: 5 degree	s (use larger for steep terrain)	
Reset Existing Ground Points to Unclassified at	t Start	
	1	

Now we can get into the real fun: Classification Tools based on mathematical models of the world in point format. Pull out the ground, vegetation and buildings. Results can be verified and adjusted as needed.

Once classified, there are some features that can be extracted.

Automatic Classification of Buildin	g/Vegetation	n Lidar Points	>
Select Unclassified Point Cloud(s) t	o Find Likely B	uilding/Ground	Points
EVT1488.las			
🗌 🔲 Only Classify Lidar Points Sele	cted in Digitize	er Tool	
Base Bin Size to Check for Planar Poi	nts: 0.4	Meters	•
ADVANCED: Threshold Values	,		_
The following parameters control h	now close to a	calculated local	best-fit plane that points
values larger than the expected e	ed a potential rror in the ele	vations):	ely vegetation area. Use
Minimum Height Above Ground:	2	meters	
Maximum Co-Planar Distance:	0.08	meters	Restore Defaults
Minimum Vegetation Distance:	0.15	meters	
Max Co-Planar Angle Difference:	5	degrees	
Peret Evisting Non-Cround Point	s to Unclassifi	ad at Start	
- React Existing Non-Ground Point	a to unudssili		
			Or Court
Specify Bounds Filter Points	by Elev/Class	/etc	OK Cancel

Lidar Feature Extraction Settings

5		
Select Point Cloud(s) to Extract Features From		
▼EVT1488.las		
L		
Resolution to Extract at: 0.5 Point Spacings		
-Building Outline Extraction Settings	Tree Extraction Settings	
Fxtract 3D Building Outlines	Extract Tree Points	
Create Separate 3D Areas for Different Poof Dieces if Possible (i.e. Very High Detail)	Minimum Tree Height:	4 meters
May Co Planar Ando Difference: 25 degrees		
Max co-hanar Angle Difference: 20 degrees	Minimum Tree Spread:	3 meters
Max Distance From Adjacent Plane: 0.25 meters	Maximum Tree Spread:	20 meters
Create Side Wall Areas Extending to Ground	Create Approximate T	ree Coverage Polygons
ADVANCED - Simplification Multiplier for Smoothing Buildings: 2		
Specify Bounds Filter Points Restore Defaults	Γ	OK Cancel
	L	



All the previous work was completed in 2d from above. There is also a 3d viewer.

👭 3D View

• 22



Flood visualization. (Not well advanced for large area flood analysis)

👯 3D View

- 0 ×



👯 3D View

- a x



👯 3D View

[
]
 [
]
]
 [
]
]
 [
]
]
]
 [
]
]
]
 [
]
]
 [
]
]
 [
]
]
 [
]
]
 [
]
]
 [
]
]
 [
]
]
 [
]
]
 [
]
]
 [
]
 [
]
]
 [
]
 [
]
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [
]
 [



– n x

LIDAR



VERMONT SOCIETY of LAND SURVEYORS

J. Thaddeus "Thadd" Eldredge *ELDREDGE SURVEYING & ENGINEERING, LLC* 1038 Main Street, Chatham, MA 02633 www.ese-llc.com